

Order verification - facts and fiction

Pavel Bochev

Computational Mathematics and Algorithms
Sandia National Laboratories

Sandia CSRI Workshop on Math Methods for V&V
August 14-16, 2007

Supported in part by



Sandia is a multiprogram laboratory operated by Sandia Corporation, a Lockheed Martin Company,
for the United States Department of Energy's National Nuclear Security Administration
under contract DE-AC04-94AL85000.

Definitions

Fact: a thing that is indisputably the case: Theory \Rightarrow Practice

Theory: under some assumptions (solution regularity, grid regularity) FE solutions should converge as $O(h^r)$ for some $r > 0$

Practice: if these assumptions are satisfied, numerical solutions converge as $O(h^r)$ too.

Fiction: a belief or statement that is false but is often held to be true because it is expedient to do so: Practice \Rightarrow Theory

Checking that numerical solutions converge as $O(h^r)$ for **smooth solutions** on a limited set of grids (**usually uniform**) is sufficient to declare that the code

- ➔ is implemented correctly
- ➔ is robust and will perform well on general grids
- ➔ will recover physical solutions that are less regular than required by convergence theory, i.e., the only side effect will be slower convergence, not reduced fidelity

I will illustrate how things can go wrong using 3 codes for the Poisson (!) equation implemented using FE on quadrilateral grids.

- Standard Galerkin method with Q1 elements
- Mixed Galerkin method with Q1-P0 elements
- Mixed least-squares method with Q1-Q1 and RT0-Q1 elements

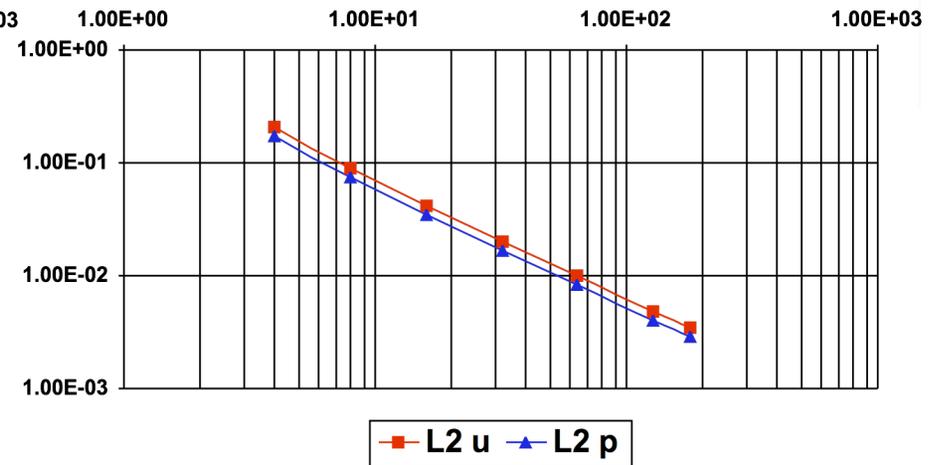
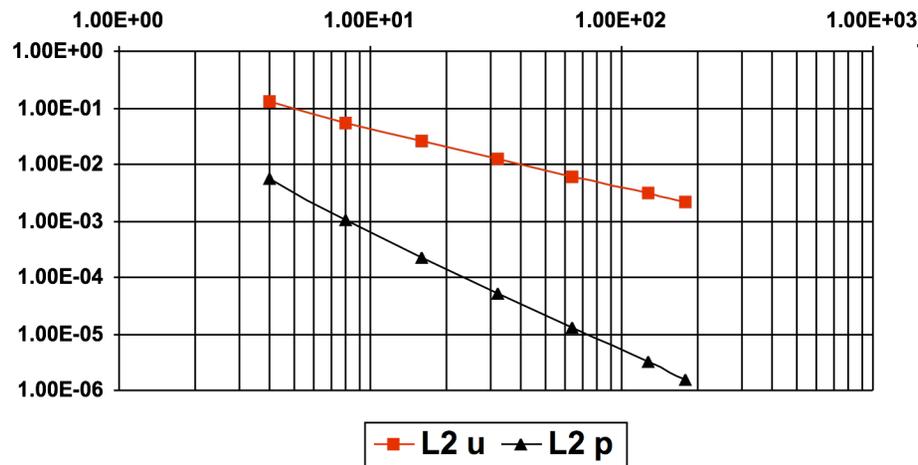
$$\begin{aligned} -\Delta\phi &= 0 \quad \text{in } \Omega \\ \phi &= 0 \quad \text{on } \Gamma \end{aligned}$$

Order verification

This is what we see on a sequence of uniform grids:

Galerkin

Mixed Galerkin



And it is exactly what the theory predicts:

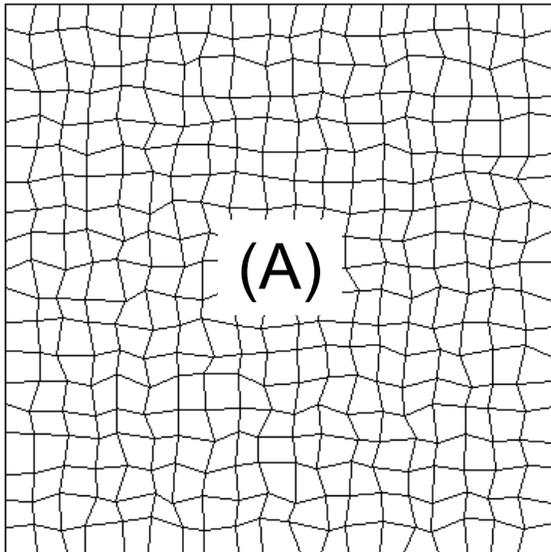
$$\|p - p^h\| = O(h^2) \text{ and } \|u - u^h\| = O(h)$$

$$\|p - p^h\| = O(h) \text{ and } \|u - u^h\| = O(h)$$

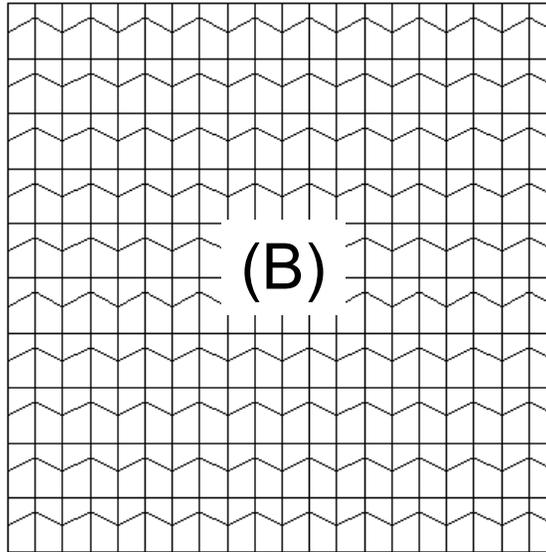
So the theory seems to check out just fine...

Let's try some other grids

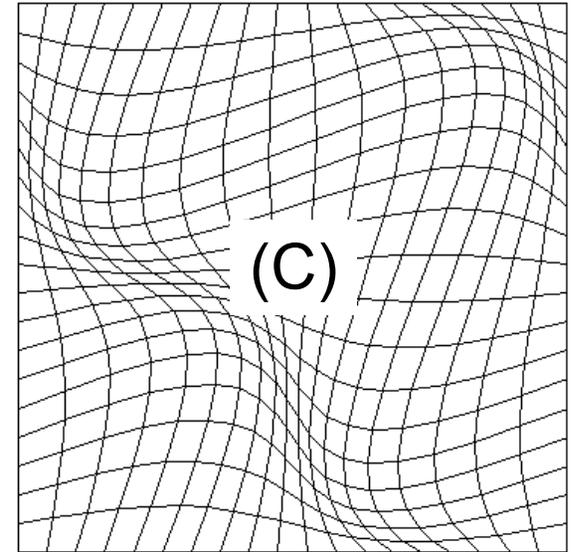
20 x 20 Random Grid



20 x 20 See-saw Grid



20 x 20 Smooth Grid



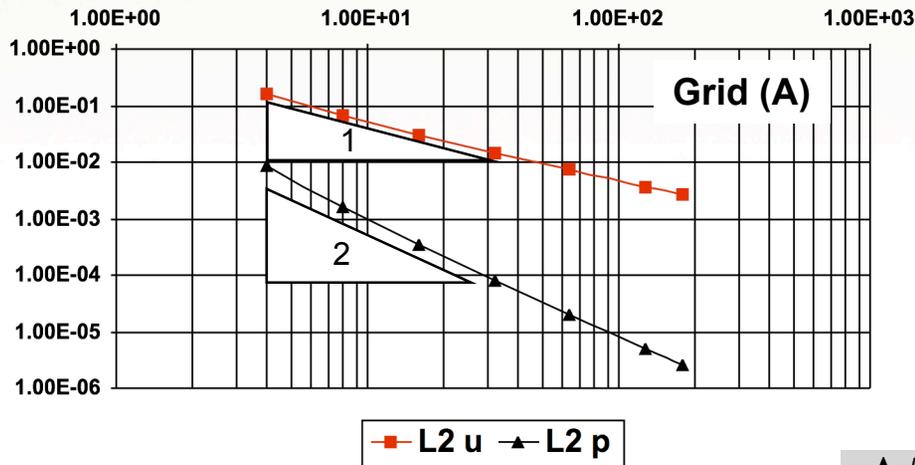
(A) & (B) are **mild perturbations** of a uniform mesh

(C) has the **worst** cell aspect ratio.

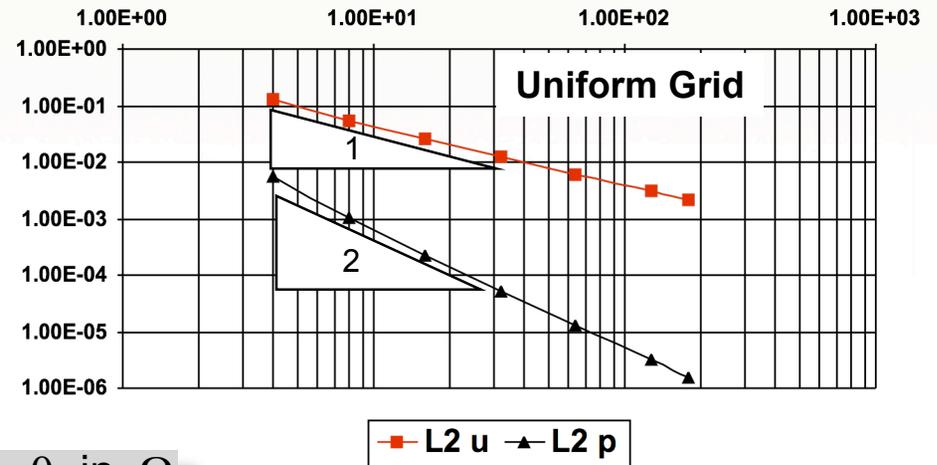
All grid sequences are uniformly regular

The Galerkin code seems to work fine

Galerkin



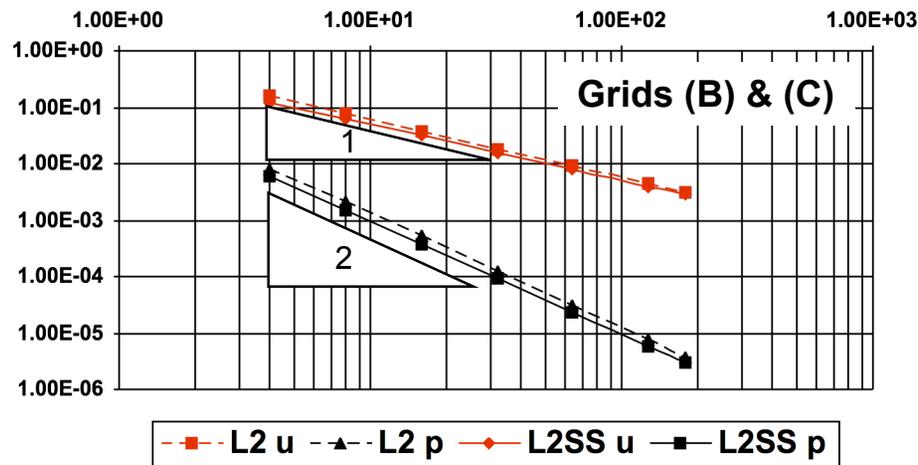
Galerkin



$$-\Delta\phi = 0 \text{ in } \Omega$$

$$\phi = 0 \text{ on } \Gamma$$

Galerkin



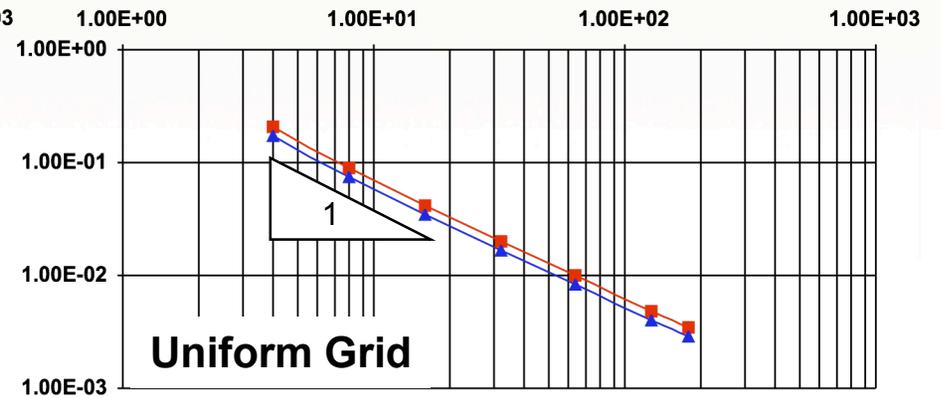
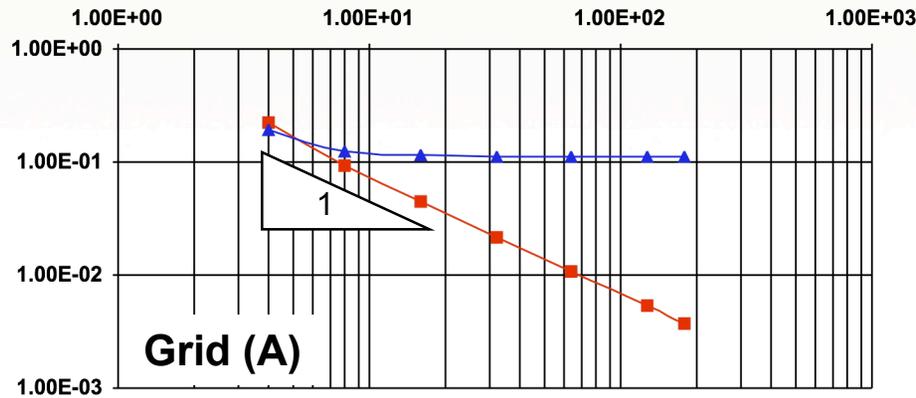
Nodal elements have comparable performance and are optimally accurate on all 3 grids

2x2 Gauss points used in all cases

But look what happens to the Mixed Galerkin!

Mixed Galerkin

Mixed Galerkin



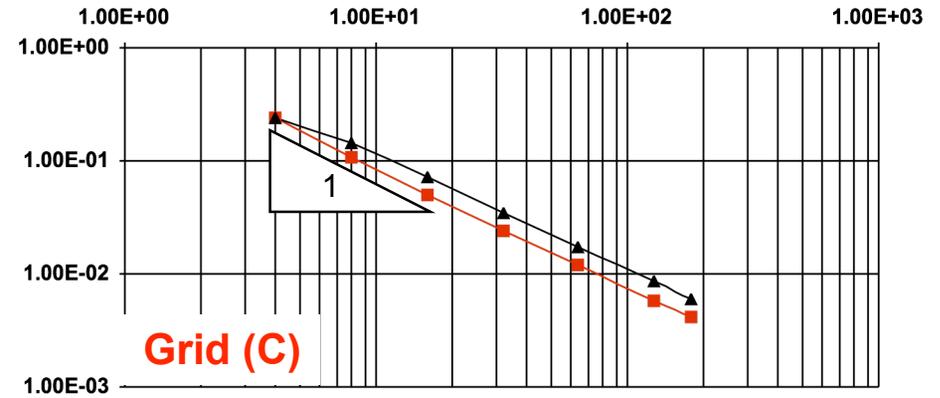
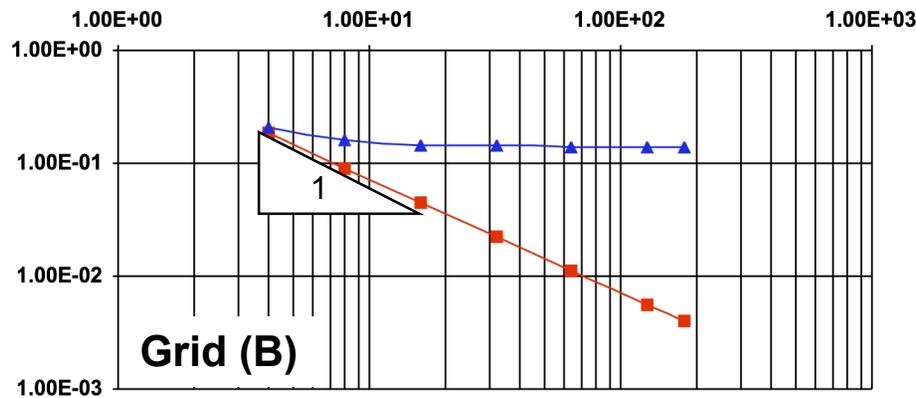
—■— L2 p —▲— L2 V

—■— L2 p —▲— L2 V

$$\begin{aligned} \nabla \cdot \mathbf{v} &= f \text{ in } \Omega \\ \mathbf{v} + \nabla \phi &= 0 \text{ in } \Omega \\ \phi &= 0 \text{ on } \Gamma \end{aligned}$$

Mixed Galerkin

Mixed Galerkin



—■— L2 p —▲— L2 V

—■— L2 p —▲— L2 V

What is going on here?

We were too quick to conclude that all is fine by checking the error bound

$$\|p - p^h\| = O(h) \text{ and } \|u - u^h\| = O(h)$$

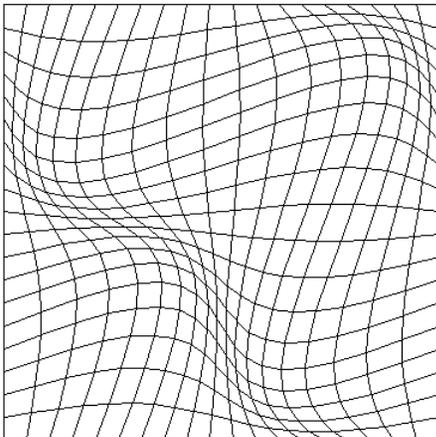
only on uniform grids. It turns out that this bound **does not hold on non-affine grids!**

Why? The RT0 space does not contain constants $\rightarrow W(\mathbf{x}) = \frac{1}{\underbrace{\det DF}_{\text{Piola Transform}}} DF \hat{W} \circ F^{-1}(\mathbf{x})$

This explains our results:

In the eyeball norm, grid **(C)** appears worse than **(A)** and **(B)**! However, the cells of **(C)** are, on the average closer to **affine** quads, than the cells of **(A)** and **(B)**!

20 x 20 Smooth Grid



- ✓ Face elements can behave **differently** from nodal elements
- ✓ Convergence studies must be carefully **designed**
- ✓ Using only uniform grids **can be inconclusive!**
- ✓ Tests must include **strongly** and **weakly** non-affine grids
- ✓ Choice of quadrature can change convergence too!

Now let's look at a different scenario

We take 2 different implementations of a mixed least-squares method:

- Mixed least-squares method with Q1-Q1 and RT0-Q1 elements

This is what we see on a sequence of uniform grids for a smooth solution:

LS vs BA	scalar		vector	
	H^1	H^1	$H(\text{div})$	$H(\text{div})$
	Q1-RT0	Q1-Q1	Q1-RT0	Q1-Q1
LS	1.01	1.00	1.00	0.99
BA	1.00	1.00	1.00	1.00

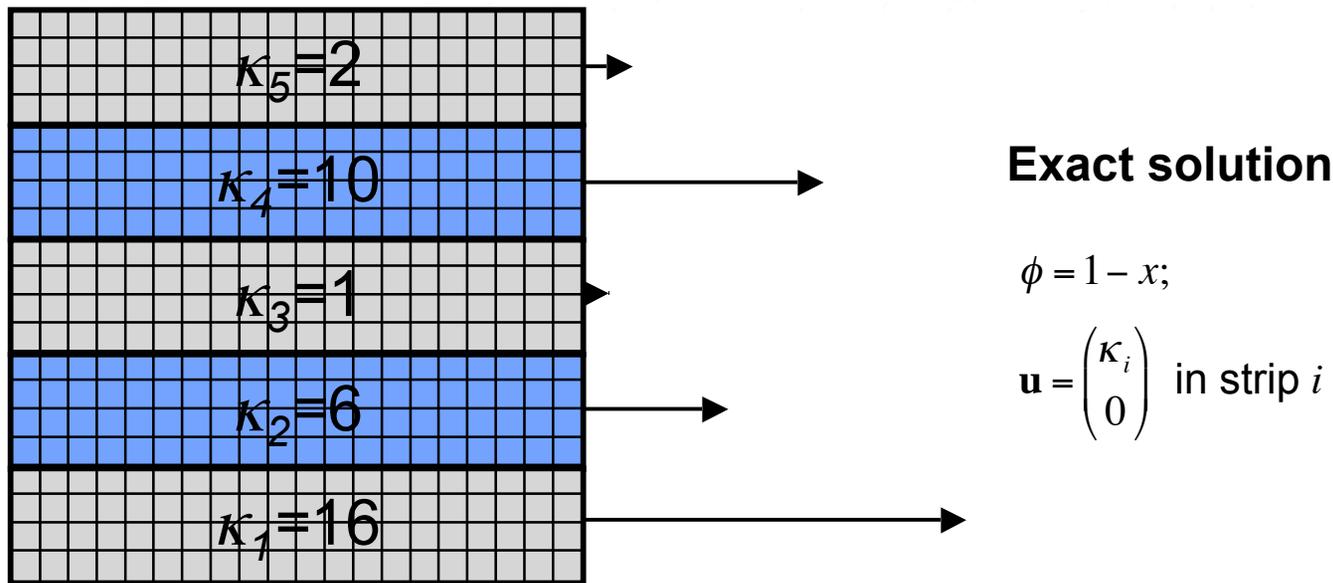
And it is exactly what the theory predicts for this method:

$$\|p - p^h\|_1 + \|\nabla \cdot (u - u^h)\| = O(h)$$

So the theory seems to check out just fine for both methods...

Let's try another (rough) solution

From: *T. Hughes, A. Masud and J. Wan, A stabilized mixed DG method for Darcy flow*

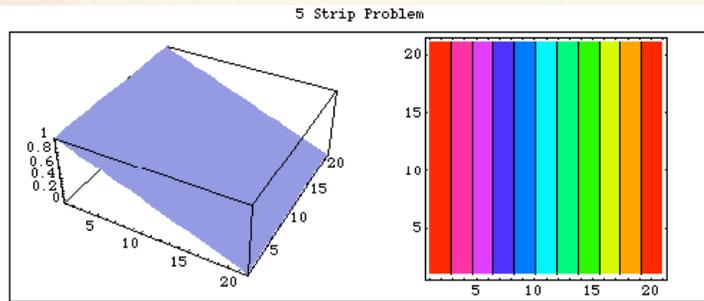


- Problem is driven by Neumann boundary condition (**normal flux**)
- Solution is **physical**, i.e., can be realized in an experiment
- Grid has 400 uniform elements **aligned with the interfaces** between the strips

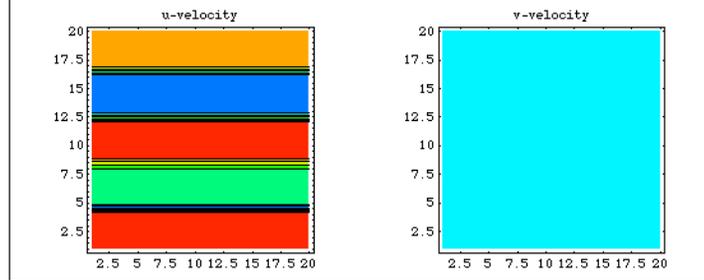
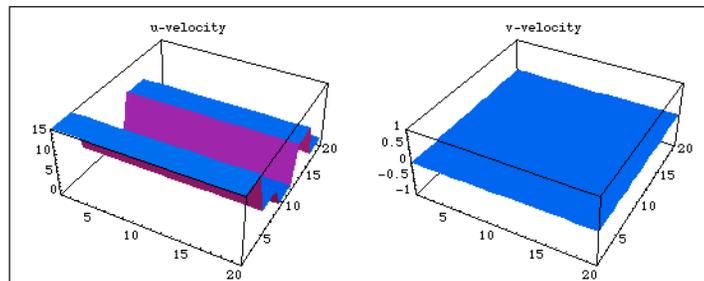
Q1-RT0

???

Q1-Q1

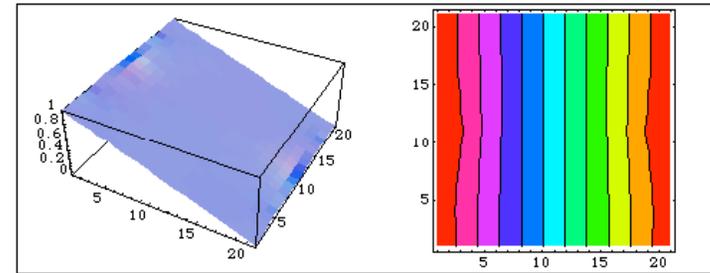


Mimetic LS Pressure

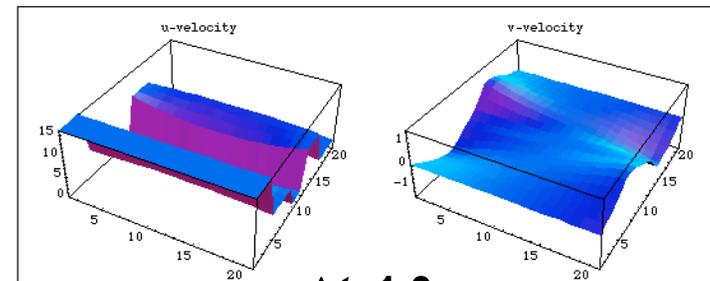


Mimetic LS Velocity

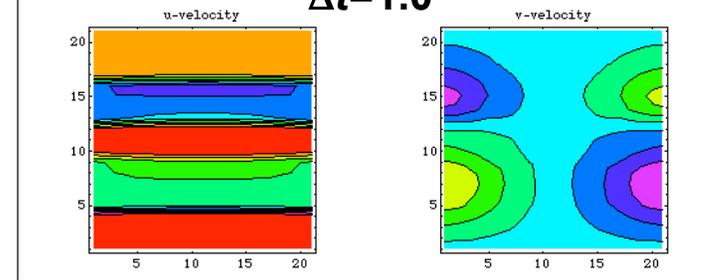
Recovers the physical solution!



Modal LS Pressure



$\Delta t=1.0$



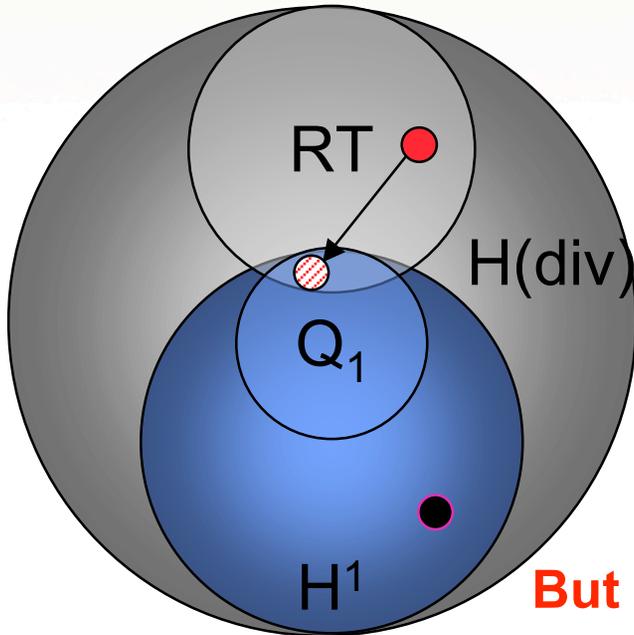
Modal LS Velocity

Recovers a spurious solution!

The trouble is, the spurious solution looks completely reasonable. Order verification did not signal any trouble for the Q1-Q1 code. Imagine this scenario in a complex multiphysics code...

This is what happens in this test:

Solution belongs to Q1-RT0 \Rightarrow **recovered by Q1-RT0 implementation**



Least-Squares solution is a projection onto the discrete space



gives the best possible approximation out of that space with respect to the energy norm

Q1-Q1 Least-Squares: gives the **best energy norm** approximation of that solution out of Q1

**But $Q_1 \subset H^1$ and H^1 has infinite co-dimension in $H(\text{div})!$
 \Rightarrow Error $>$ const. \Rightarrow Q1-Q1 LS will never converge!**

- ✓ Convergence for smooth solutions **does not guarantee approximation** of other solutions!
- ✓ Testing on rough but physically meaningful solutions **should be part of the verification**
- ✓ This is **accepted practice in hydro codes** which are expected to work for rough solutions
- ✓ This is **seldom practiced** in codes for elliptic problems despite the fact that in many cases we can only expect, e.g., $H(\text{curl})$ or $H(\text{div})$ solution (discontinuous materials, etc)